## Role of Magnetic Field

It drives evolution of flow velocity.

$$\rho \, \frac{d\mathbf{v}}{dt} = \frac{1}{\mu_0} \left( \nabla \times \mathbf{B} \right) \times \mathbf{B}$$

#### Magnetic field in MHD

 $\Rightarrow$  two components of  $j \times B$  force (magnetic tension & magnetic pressure)

Decompose  $\mathbf{j} \times \mathbf{B} = \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B}$  into two components:

A formula of vector differentiation:

$$\nabla (X \bullet Y) = (Y \bullet \nabla) X + (X \bullet \nabla) Y + Y \times (\nabla \times X) + X \times (\nabla \times Y)$$

Substitute **X** = **B**, **Y** = **B** into this formula, then we have

$$\nabla (B \bullet B) = (B \bullet \nabla) B + (B \bullet \nabla) B + B \times (\nabla \times B) + B \times (\nabla \times B)$$

This is transformed into

$$(\nabla \times \mathbf{B}) \times \mathbf{B} = (\mathbf{B} \cdot \nabla) \mathbf{B} - \nabla \left(\frac{\mathbf{B}^2}{2}\right)$$

$$j \times \mathbf{B} = \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B}$$

$$= \underbrace{\frac{1}{\mu_0} (\mathbf{B} \cdot \nabla) \mathbf{B}}_{\text{tension part}} - \nabla \underbrace{\left(\frac{\mathbf{B}^2}{2\mu_0}\right)}_{\text{pressure part}}$$

# *Magnetic tension:* $F_T = \frac{1}{\mu_0} (B \bullet \nabla) B$

$$(B \bullet \nabla) B = B \hat{s} \bullet \nabla (B \hat{s})$$

$$= B \frac{\partial}{\partial s} (B \hat{s})$$

$$= (B \frac{\partial}{\partial s}) \hat{s} + B^2 \frac{\partial}{\partial s} \hat{s}$$

$$= (B \frac{\partial}{\partial s}) \hat{s} + B^2 \frac{\hat{n}}{R_c}$$

$$\hat{s}(s) = \frac{\partial}{\partial s} (\hat{s}) \hat{s}(s)$$

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 $\hat{S}(S)$ ... tangential vector along a magnetic field line (unit vector)

$$\mathbf{\hat{s}}(s) = B(s) \ \mathbf{\hat{s}}(s)$$

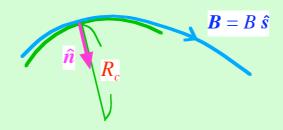
$$\mathbf{\hat{n}}(s)$$

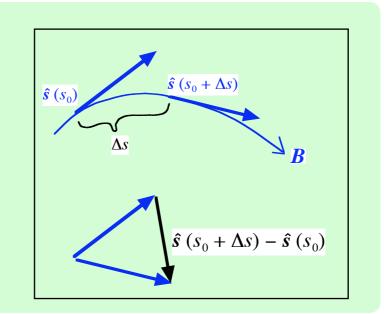
$$\hat{s} \cdot \frac{\partial \hat{s}}{\partial s} = \frac{1}{2} \frac{\partial}{\partial s} (\hat{s} \cdot \hat{s}) = \frac{1}{2} \frac{\partial}{\partial s} (1) = 0$$

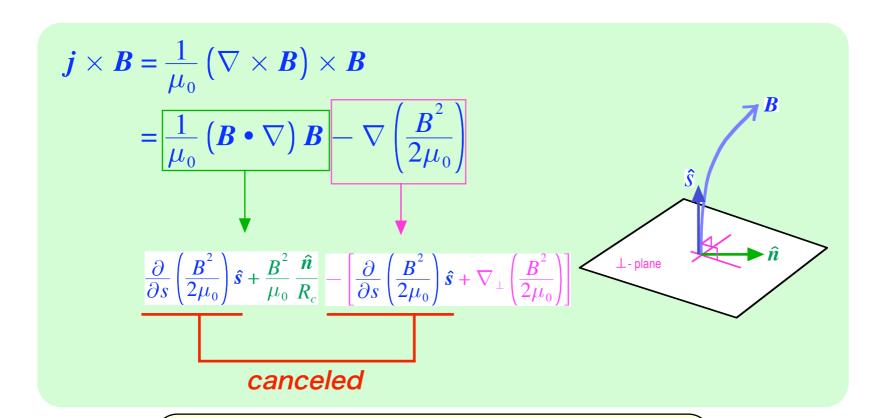
$$\Rightarrow \hat{s} \perp \frac{\partial \hat{s}}{\partial s} \Rightarrow \frac{\partial \hat{s}}{\partial s} // \hat{n} \text{ normal vector (unit vector)}$$

$$\frac{\partial \hat{\mathbf{s}}}{\partial s} = \lim_{\Delta s \to 0} \frac{\hat{\mathbf{s}} (s_0 + \Delta s) - \hat{\mathbf{s}} (s_0)}{\Delta s}$$
$$= \kappa \hat{\mathbf{n}} = \frac{\hat{\mathbf{n}}}{R_c}$$

 $\kappa$ ... curvature,  $R_c \equiv \frac{1}{\kappa}$ ... curvature radius







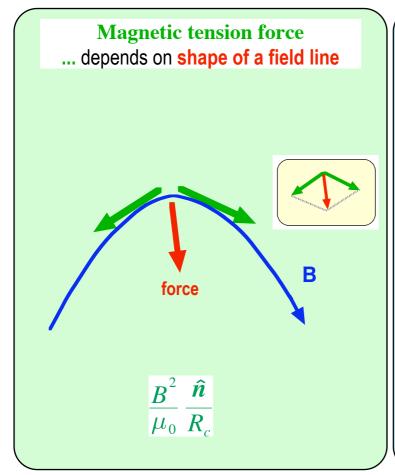
$$\mathbf{j} \times \mathbf{B} = \frac{B^2}{\mu_0} \frac{\hat{\mathbf{n}}}{R_c} - \nabla_{\perp} \left( \frac{B^2}{2\mu_0} \right)$$

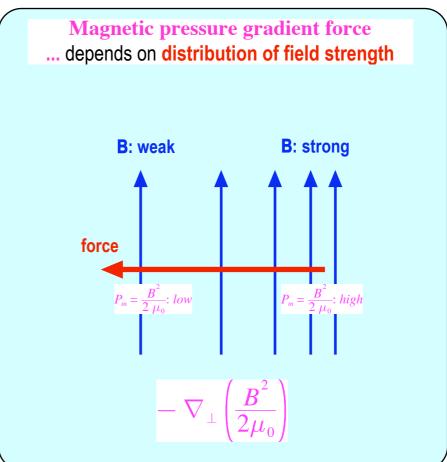
magnetic tension force

magnetic pressure gradient force

Both magnetic tension force and magnetic pressure gradient force work in the direction perpendicular to magnetic field.

### Features of magnetic tension and magnetic pressure

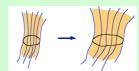




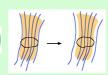
## Summary of the roles of $E^{MHD}$ and B in MHD

Electric field => drives evolution of magnetic field through  $\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}^{MHD}$ 

$$-\nabla \times \boldsymbol{E}_{conv} = \nabla \times (\boldsymbol{v} \times \boldsymbol{B})$$



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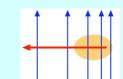


Magnetic Field => drives evolution of flow velocity through  $\rho \frac{d\mathbf{v}}{dt} = \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B}$ 

$$\boldsymbol{F}_{t} = \frac{\boldsymbol{B}^{2}}{\mu_{0}} \, \frac{\boldsymbol{\hat{n}}}{R_{c}}$$



$$\boldsymbol{F}_{m} = -\nabla_{\perp} \left( \frac{\boldsymbol{B}^{2}}{2\mu_{0}} \right)$$





#### What is a wave?

It is a time-dependent phenomenon in which a **physical state** is transported from one location to other locations through a medium (what is transported is **physical state**, not physical object).

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