

Motion of a charged particle in  $B_{\parallel}$ - *direction*

(Mirror effect)

# Mirror effect

$\mathbf{B}$ : magnetic field (nonuniform & constant, weakly curved shape)

$\mathbf{v}$ : particle's velocity

$m, q$ : particle's mass & charge

Gyration-average Lorentz force  $\langle q \mathbf{v} \times \mathbf{B} \rangle$ :

$$\begin{aligned} \mathbf{F} &= q (\mathbf{v}_r \hat{\mathbf{r}} + \mathbf{v}_\theta \hat{\boldsymbol{\theta}} + \mathbf{v}_z \hat{\mathbf{z}}) \times (\mathbf{B}_r \hat{\mathbf{r}} + \mathbf{B}_z \hat{\mathbf{z}}) \\ &= q (\mathbf{v}_r \mathbf{B}_z \hat{\mathbf{r}} \times \hat{\mathbf{z}} + \mathbf{v}_\theta \mathbf{B}_r \hat{\boldsymbol{\theta}} \times \hat{\mathbf{r}} + \mathbf{v}_\theta \mathbf{B}_z \hat{\boldsymbol{\theta}} \times \hat{\mathbf{z}} + \mathbf{v}_z \mathbf{B}_r \hat{\mathbf{z}} \times \hat{\mathbf{r}}) \\ &= q [\mathbf{v}_\theta \mathbf{B}_z \hat{\mathbf{r}} + (\mathbf{v}_z \mathbf{B}_r - \mathbf{v}_r \mathbf{B}_z) \hat{\boldsymbol{\theta}} - \mathbf{v}_\theta \mathbf{B}_r \hat{\mathbf{z}}] \end{aligned}$$

$$\langle \hat{\mathbf{r}} \rangle = 0, \langle \hat{\boldsymbol{\theta}} \rangle = 0 \quad q \gtrless 0 \rightarrow \mathbf{v}_\theta \lesg 0$$

$$\langle \mathbf{F} \rangle_{\text{gyration}} = |q| |\mathbf{v}_\theta| \mathbf{B}_r \hat{\mathbf{z}}$$

$$\mathbf{F}_z \approx |q| |\mathbf{v}_\theta| \mathbf{B}_r(r_G, z)$$

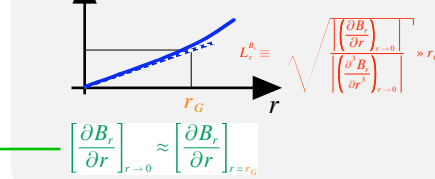
Taylor expansion of  $B_r(r, z)$  around  $r = 0$ :

odd function of  $r$

$$B_r(r, z) = \underbrace{B_r(0, z)}_{=0} + \left[ \frac{\partial B_r(r, z)}{\partial r} \right]_{r=0} r + \dots \approx 0$$

$$\frac{B_r(r_G, z)}{r_G} \approx \left[ \frac{\partial B_r(r, z)}{\partial r} \right]_{r=r_G}$$

0th and/or 1st-order terms are considered within  $0 \leq r \leq r_G$ .



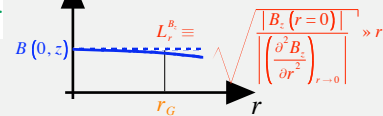
Taylor expansion of  $B_z(r, z)$  around  $r = 0$ :

even function of  $r$

$$B_z(r, z) = \underbrace{B_z(0, z)}_{=0} + \left[ \frac{\partial B_z(r, z)}{\partial r} \right]_{r=0} r + \dots = B(0, z)$$

1st-order term is 0 when  $r \rightarrow 0$  (for smoothness)

0th and/or 1st-order terms are considered within  $0 \leq r \leq r_G$ .



Divergence free condition ( $\nabla \cdot \mathbf{B} = 0$ ) at  $r = r_G$ :

$$\nabla \cdot \mathbf{B} \Big|_{r=r_G} = \left[ \frac{\partial B_r(r, z)}{\partial r} \right]_{r=r_G} + \frac{B_r(r_G, z)}{r_G} + \left[ \frac{\partial B_z(r, z)}{\partial z} \right]_{r=r_G} = 0$$

$$\frac{B_r(r_G, z)}{r_G} \approx -\frac{1}{2} \left[ \frac{\partial B_z(r, z)}{\partial z} \right]_{r=r_G} \approx -\frac{1}{2} \frac{\partial B(0, z)}{\partial z}$$

$$B_r(r_G, z) \approx -\frac{r_G}{2} \frac{\partial B(0, z)}{\partial z}$$

$$F_z \approx -\frac{m v_\theta^2}{2 B(0, z)} \frac{\partial B(0, z)}{\partial z}$$

$$r_G = \frac{|\mathbf{v}_\theta|}{\omega_B}, \quad \omega_B \equiv \frac{|q| B(0, z)}{m}$$

axisymmetric, not helical

$$B_z \gg B_r > 0, B_\theta = 0$$

