

# 1) Collisional equilibrium case

In this case collision does NOT change the distribution function (**collisional equilibrium**). In a local frame fixed to  $\Delta V$  at  $\mathbf{x} = \mathbf{x}_0$ , it is given by

$$\left( \frac{\delta f(\mathbf{x}_0, \mathbf{v}, t)}{\delta t} \right)_c = 0 \quad \text{with } \mathbf{v} = \mathbf{w}$$

$$\left( \frac{\delta f(\mathbf{x}_0, \mathbf{v}, t)}{\delta t} \right)_c = \int_{V, \Omega} f(\mathbf{x}_0, \mathbf{v}') f(\mathbf{x}_0, \mathbf{v}_1) \sigma_{\mathbf{v}', \mathbf{v}_1 \rightarrow \mathbf{v}, \mathbf{v}_1}(\Omega) |\mathbf{v}' - \mathbf{v}_1| d\Omega d^3 v_1 - f(\mathbf{x}_0, \mathbf{v}) f(\mathbf{x}_0, \mathbf{v}_1) \sigma_{\mathbf{v}, \mathbf{v}_1 \rightarrow \mathbf{v}', \mathbf{v}_1}(\Omega) |\mathbf{v} - \mathbf{v}_1| d\Omega d^3 v_1$$

existence probability of a particle with  $\mathbf{v}'$   
existence probability of a particle with  $\mathbf{v}$

existence probability of a particle with  $\mathbf{v}_1$   
existence probability of a particle with  $\mathbf{v}$

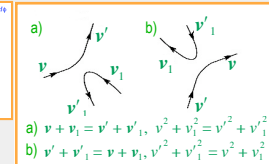
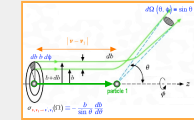
occurrence rate of  $\mathbf{v}' \Rightarrow \mathbf{v}$  — occurrence rate of  $\mathbf{v} \Rightarrow \mathbf{v}'$

$$\left[ \frac{\delta f(\mathbf{x}_0, \mathbf{v}, t)}{\delta t} \right]_c = 0 \Leftrightarrow f(\mathbf{x}_0, \mathbf{v}') f(\mathbf{x}_0, \mathbf{v}_1) - f(\mathbf{x}_0, \mathbf{v}) f(\mathbf{x}_0, \mathbf{v}_1) = 0$$

occurrence probability of a collisional process  $\mathbf{v}', \mathbf{v}_1 \rightarrow \mathbf{v}, \mathbf{v}_1$

= occurrence probability of a collisional process  $\mathbf{v}, \mathbf{v}_1 \rightarrow \mathbf{v}', \mathbf{v}_1$

$$\sigma_{\mathbf{v}', \mathbf{v}_1 \rightarrow \mathbf{v}, \mathbf{v}_1}(\Omega) |\mathbf{v}' - \mathbf{v}_1| d\Omega d^3 v_1 = \sigma_{\mathbf{v}, \mathbf{v}_1 \rightarrow \mathbf{v}', \mathbf{v}_1}(\Omega) |\mathbf{v} - \mathbf{v}_1| d\Omega d^3 v_1$$



When the distribution function depends on the magnitude of velocity, but does not depend on its direction (**isotropic random motion**),

$$f(\mathbf{v}) \Rightarrow f(v^2), f(\mathbf{v}) f(\mathbf{v}_1^2) - f(\mathbf{v}) f(\mathbf{v}_1) = 0 \Rightarrow f(v^2) f(v_1^2) - f(v^2) f(v_1^2) = 0$$

$$f(v^2) f(v_1^2) - f(v^2) f(v_1^2) = 0, v^2 + v_1^2 = v'^2 + v_1'^2 \Rightarrow f(v^2) = C_0 e^{-\alpha v^2}$$

This gives **Maxwellian distribution function**  $f_{MW}(\mathbf{v})$  with  $\int_{\mathbf{v}} f_{MW} d^3 v = n$  and  $\frac{1}{2} m \langle |\mathbf{w}|^2 \rangle_{MW} = \frac{3}{2} k_B T$ :

$$f_{MW}(\mathbf{v}) \equiv n \left( \frac{m}{2\pi k_B T} \right)^{\frac{3}{2}} e^{-\frac{m |\mathbf{v}|^2}{2 k_B T}}$$

Relation between temperature and random motion

Definition of temperature

Gas pressure and internal energy density are then expressed using temperature (here we use  $\mathbf{v} = \mathbf{w}$ ):

$$P \equiv \frac{1}{3} n m \langle |\mathbf{w}|^2 \rangle_{MW} = n k_B T \quad \dots \text{equation of state is derived from Maxwellian distribution}$$

$$\rho \mathcal{E} \equiv \frac{1}{2} n m \langle |\mathbf{w}|^2 \rangle_{MW} = \frac{3}{2} n k_B T$$

When  $f = f_{MW}$ , diffusion terms disappear... **no diffusion\*** in the **collisional equilibrium case**

$$f = f_{MW} \rightarrow \begin{cases} \pi_{ik} = 0 \rightarrow \Psi = 0 \\ \mathcal{S}_k \equiv \rho \left\langle \frac{1}{2} |\mathbf{w}|^2 w_k \right\rangle = 0 \end{cases}$$

\*Isotropic random motion ( $\langle w_1^2 \rangle = \langle w_2^2 \rangle = \langle w_3^2 \rangle$ ) is assumed.

When a locally uniform average flow exists, the Maxwellian distribution is given by (via **Galilei transformation** ( $\mathbf{v} = \mathbf{u} + \mathbf{w}$ ,  $d^3v = d^3w$ ))

$$f_{MW}(\mathbf{v}) = n \left( \frac{m}{2\pi k_B T} \right)^{\frac{3}{2}} e^{-\frac{m[(v_x - u_x)^2 + (v_y - u_y)^2 + (v_z - u_z)^2]}{2k_B T}} \longrightarrow \langle \mathbf{v} \rangle = \frac{\int (\mathbf{u} + \mathbf{w}) f_{MW}(\mathbf{w}) d^3w}{\int f_{MW}(\mathbf{w}) d^3w} = \mathbf{u}$$

When  $f = f_{MW}$  at every  $\Delta V$  and each time, it gives **ideal fluid system** governed by **Euler equations**:

### Euler equations

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_k} (\rho u_k) = 0$$

$$\frac{\partial}{\partial t} (\rho u_i) + \frac{\partial}{\partial x_k} (\rho u_i u_k + P \delta_{ik}) = \rho \frac{\langle F_i \rangle}{m}$$

$$\frac{\partial}{\partial t} (\rho \mathcal{E}) + \frac{\partial}{\partial x_k} (\rho \mathcal{E} u_k) = -P \frac{\partial u_k}{\partial x_k}$$

$$\rho \mathcal{E} \equiv \frac{1}{2} \rho \langle w_i w_i \rangle = \frac{1}{2} \rho \langle |\mathbf{w}|^2 \rangle = \frac{3}{2} P$$

... **5 equations for 6 quantities**  $\rho, u_i, P, T$

### closure relation

$$P = \frac{\rho}{m} k_B T$$

... **1 equation**